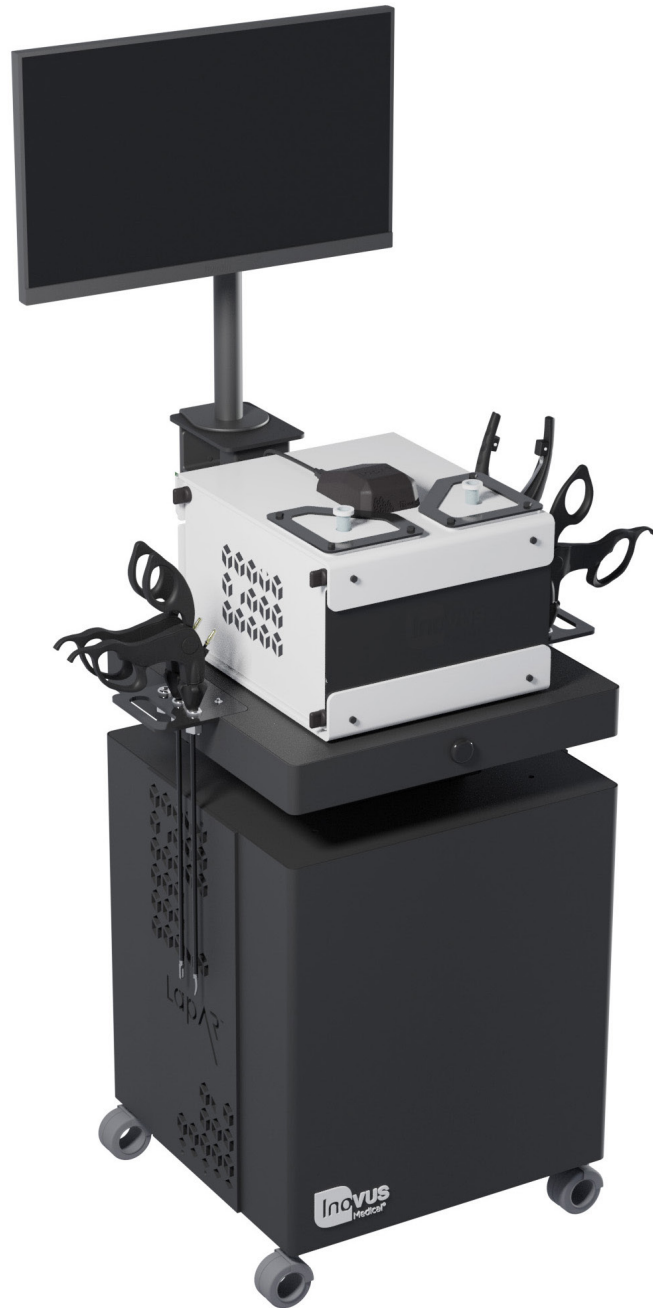


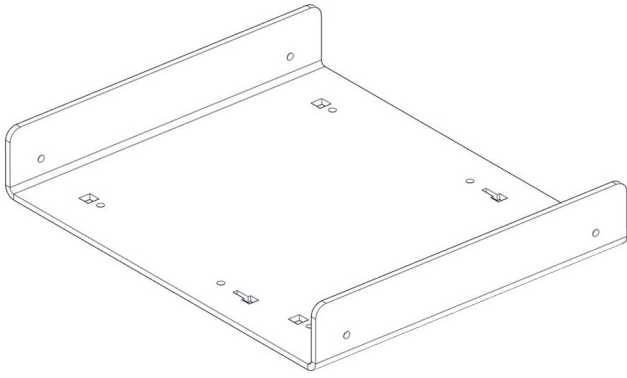


Accessible | Affordable | Functional

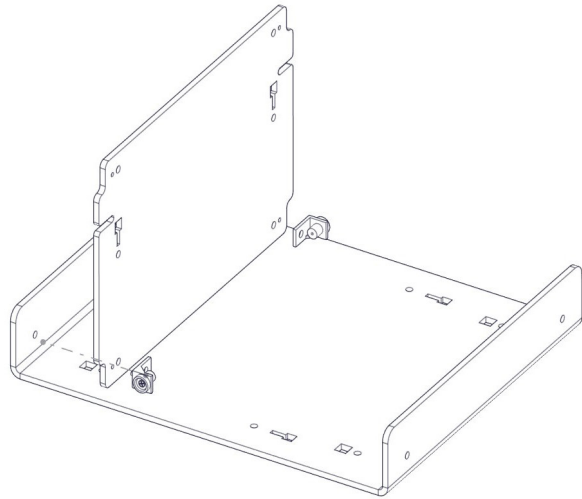


Lapar

Setup Manual

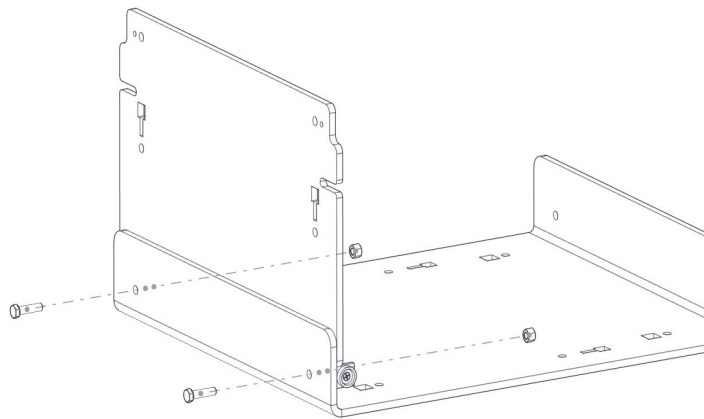


1 | When opening your simulator it is recommended that you unpack all package contents and arrange them before starting construction. Once you have done this, take the first part labelled AR20_BTM01 and lay it on a secure flat surface.



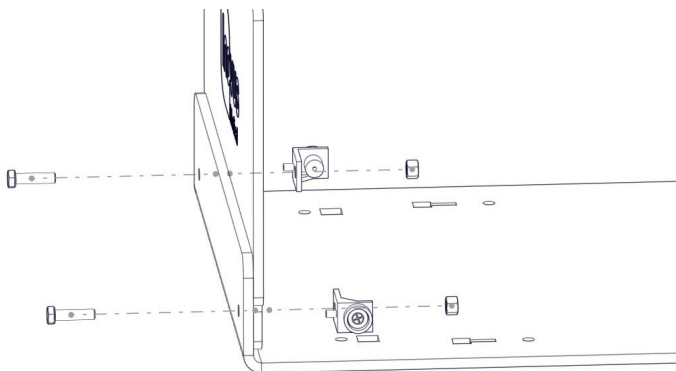
2 | Now take the following parts:
MA01 x2
AR20_U02 x1
WN14 x2
M5B24 x2.

Using the image as a guide, pay close attention to the part orientation in this step or you will have to undo work at a later stage.

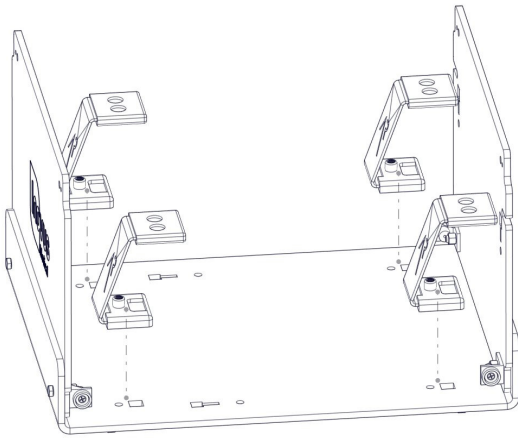


3 | MA01 x2
M5B24 x2
WN14 x2

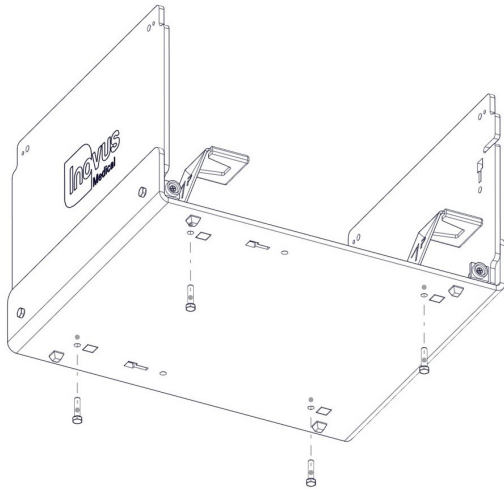
(Use the pin on part MA01 to find the correct position).



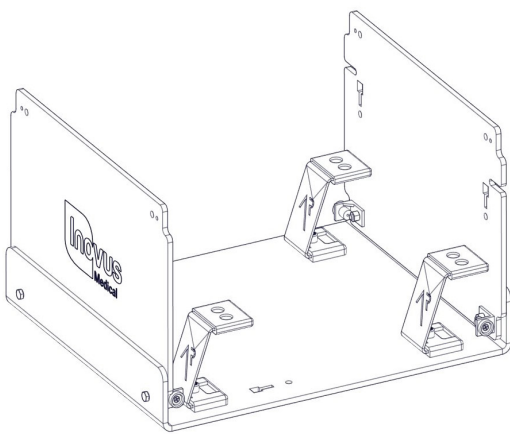
4 | Repeat the last two steps with the same parts on the front panel AR20_U01 as shown in the image.



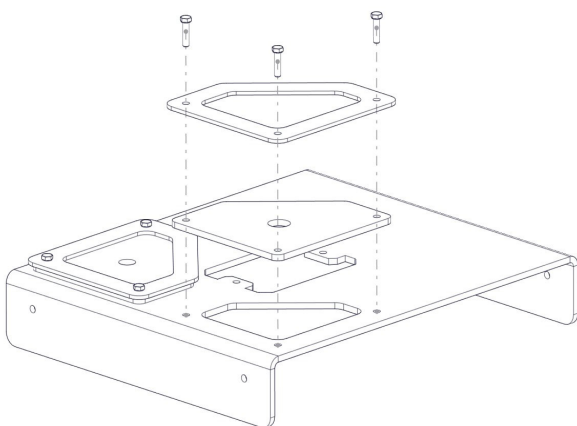
- 5 | Take 4x AR20_M-BKT, position them in the keys provided. In a practical sense this will need to be done one at a time with the simulator positioned on its side.



- 6 | Using 4x M5B24 screw each AR20_M-BKT into position on the base. These parts are threaded for ease of assembly.



- 7 | At this stage the simulator should look exactly like the reference image. If something appears to be incorrect, go back through the steps again.



- 8 | Locate the following parts:

AR20_TPBO1 x1

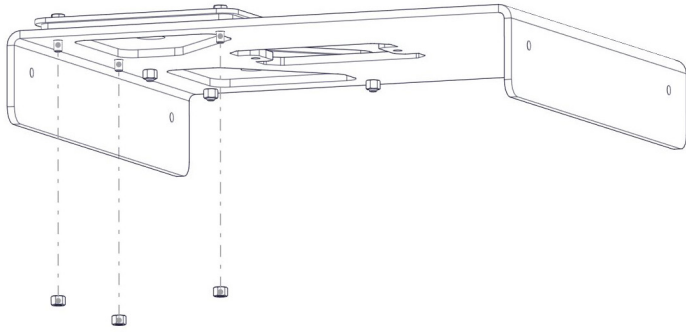
AR20_BKT x2

AR20_SK x2

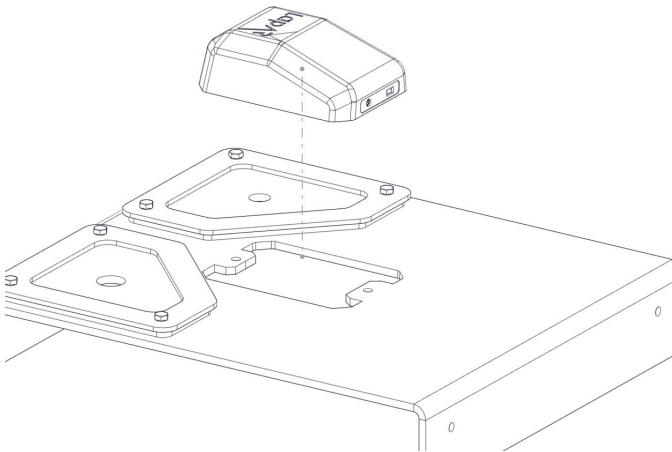
M5B24 x6

WN14 x6

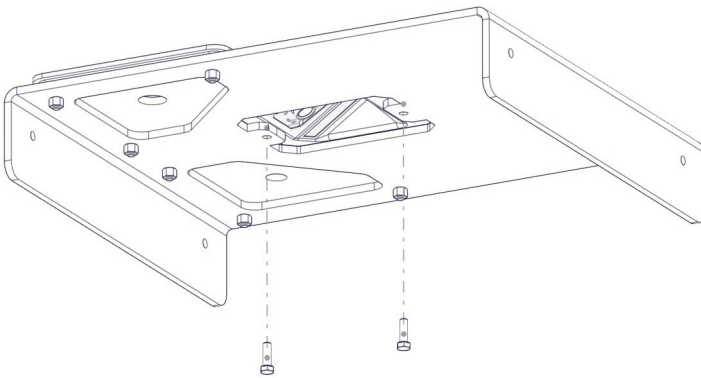
Placing the AR20_SK on to the top surface of the AR20_TPBO1 ensure that the holes align correctly. You can now position the black AR20_BKT on top of the silicone skin, pushing three M5B24 through the holes. Now move to the next step.



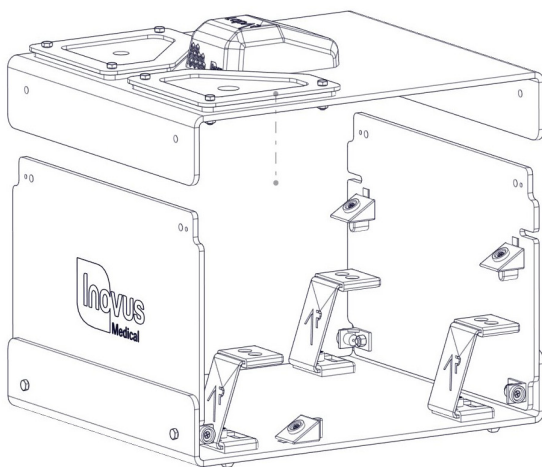
- 9 | Now attach 3x WN14 to the bolts coming through the bottom surface. Repeat this process on the opposite side to complete the assembly.



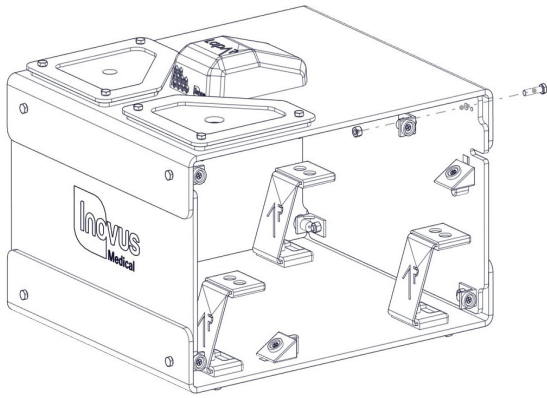
- 10 | Remove the AR20_CAM from its packaging and place into position as shown.



- 11 | Take 2x M5B24 bolts and affix the AR20_CAM into position. DO NOT plug-in at this stage.

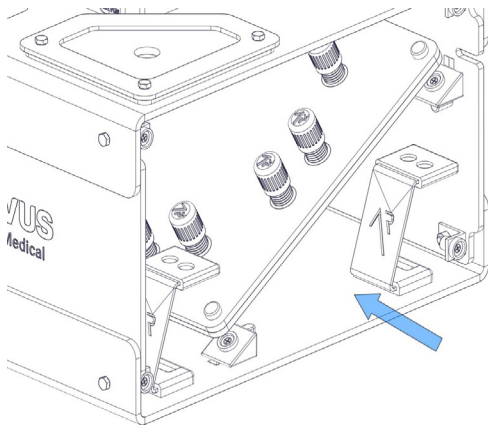


- 12 | Take the sub-assembly from the last four steps and place it over the upright panels of the simulator as shown.

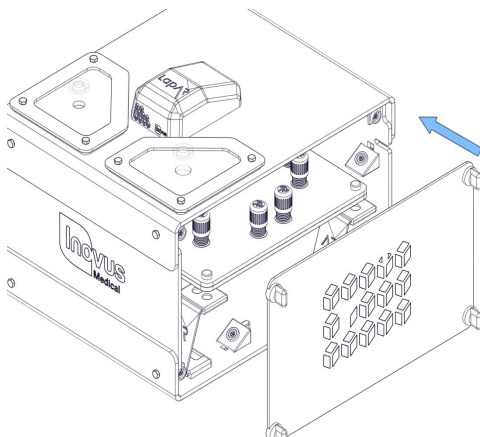


- 13 | Locate following parts:
 MA01 x4
 WN14 x4
 M5B24 x4

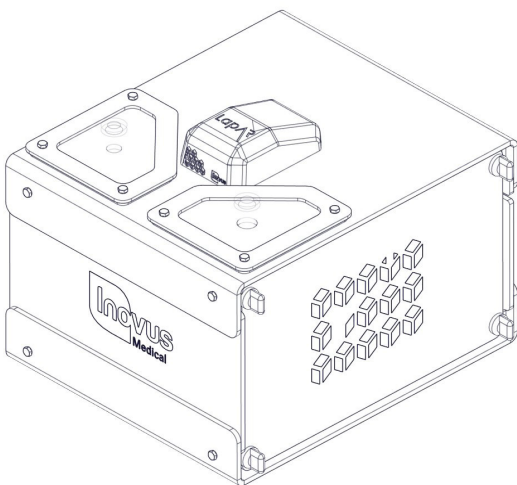
Repeat the process from steps 2,3 & 4. Do this on each corner so that a magnet is in place for the side panels to connect into.



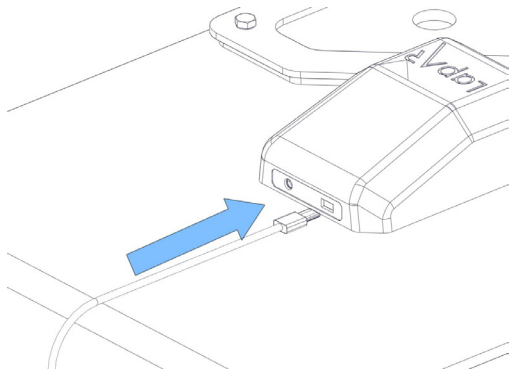
- 14 | It is important to note that the simulator is capable of multiple platform positions. When inserting AR20_TAB you will most commonly use the angled base for Augmented Reality applications.



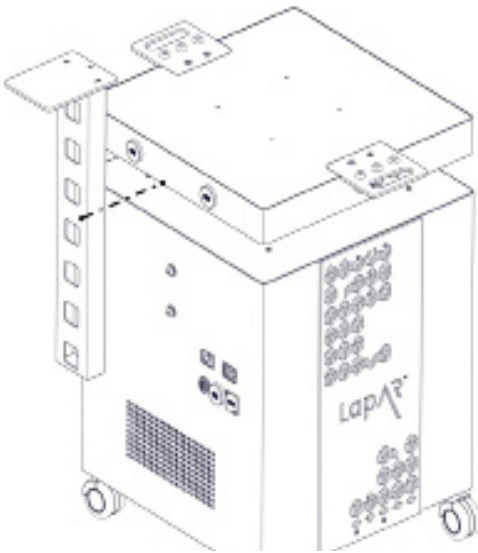
- 15 | You will use the flat platform for LapPass[®] and any other non-AR tasks. Enterprise users can use this for any tasks they like, including those where electro-surgical instruments are required.



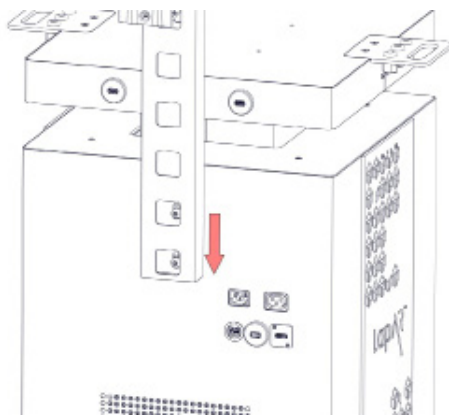
- 16 | Snap into place both side panels and move on.



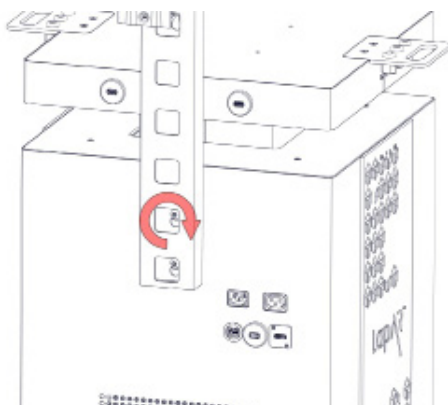
17 | Connect the USB micro into the back of the camera.



18 | Start the assembly of your portable trolley system by unscrewing the M8 bolts at the rear of chassis so that you have around 3-4mm of space between the head of the bolt and the chassis wall. You can do this using the allen key provided. Take the L shaped screen bracket and place it onto the M8 bolts as shown.

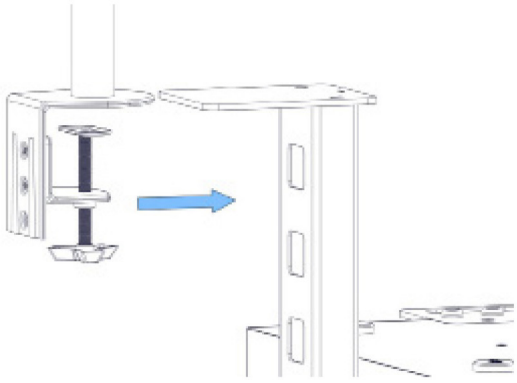


19 | Drop the bracket onto the bolts.

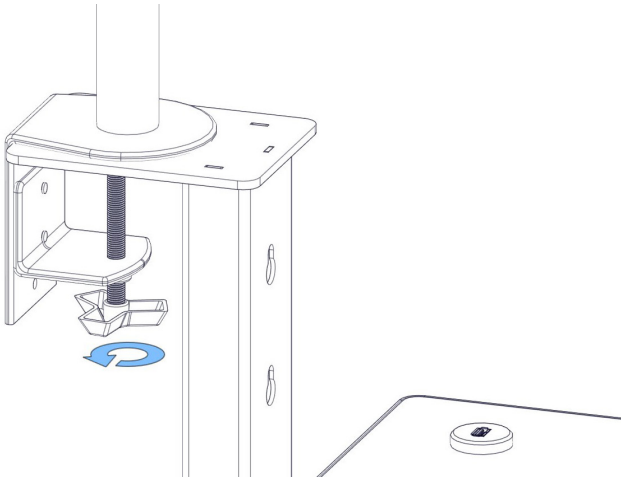


20 | Screw the bolts tight using the allen key provided. Be careful not to overtighten at this stage.

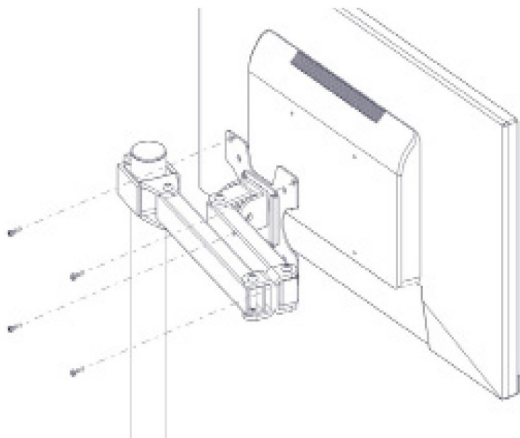
- 21| Take the assembled monitor bracket and clamp it in position as shown.



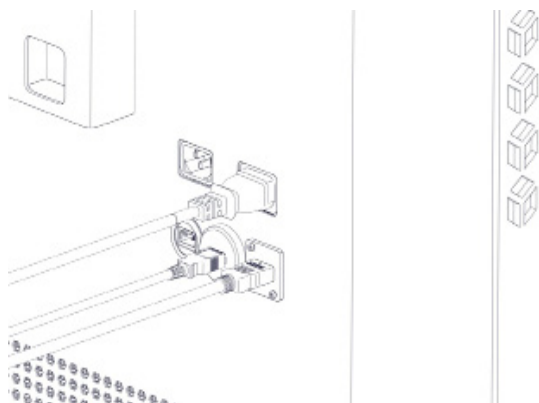
- 22| Screw the clamp until tight.

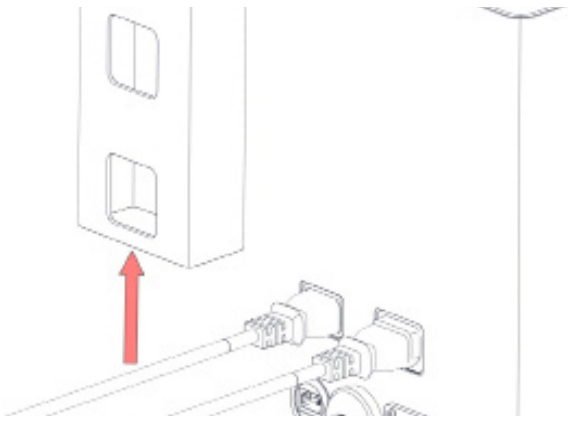


- 23| Attach the monitor screen using the 4x M4 bolts provided.

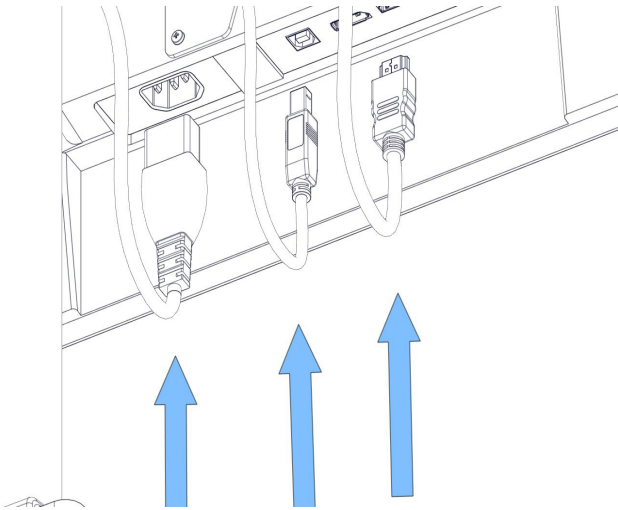


- 24| As shown in the image, plug in the IEC, HDMI & USB cables.

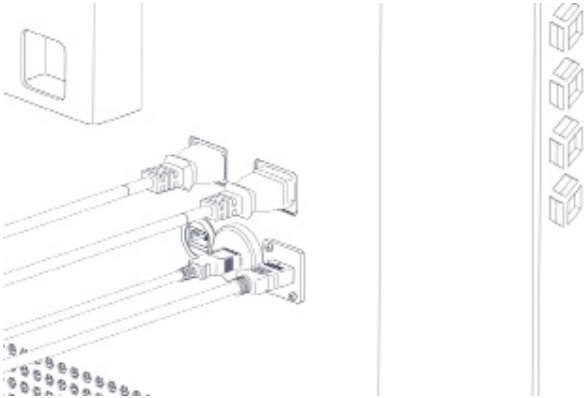




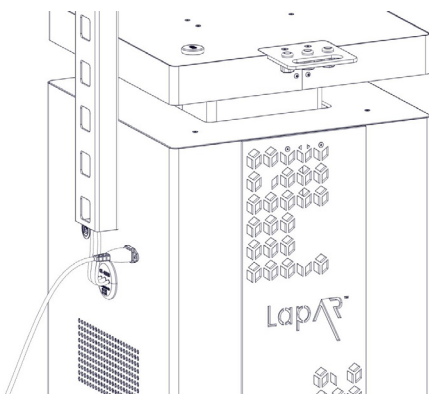
25 | Carefully thread the 3 wires we plugged in during the previous step up through the L shaped bracket and onto the monitor bracket. Move to the next step.



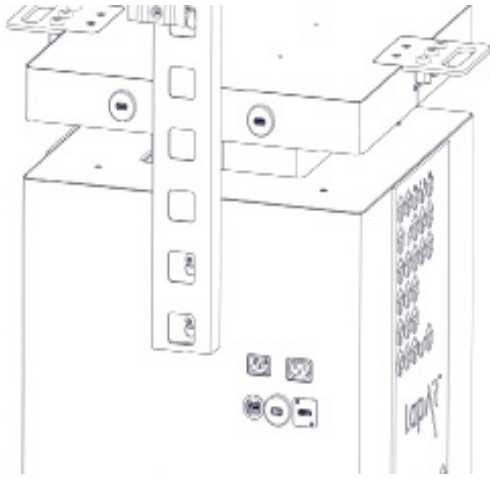
26 | Position the wires as such and plug in to the appropriate socket.



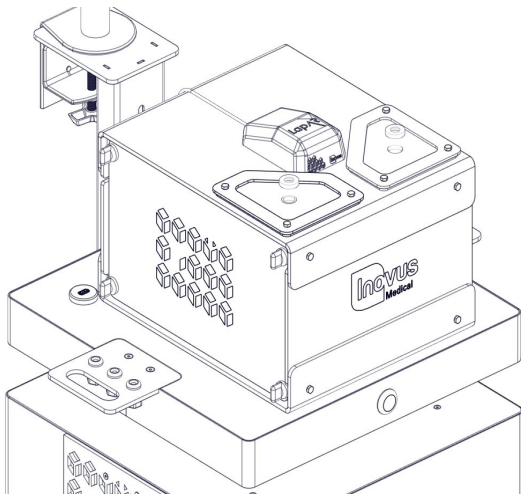
27 | Plug the IEC connector into the back of the system.



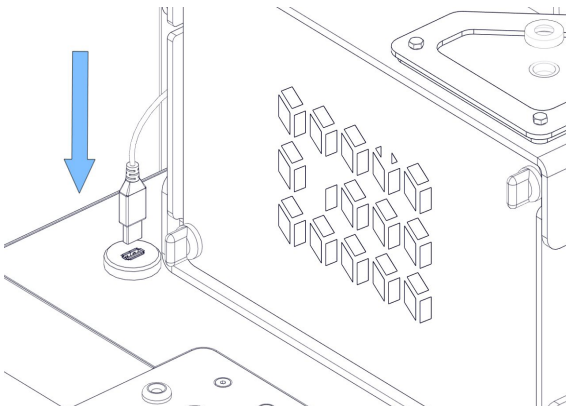
28 | Plug the connector into the mains power.



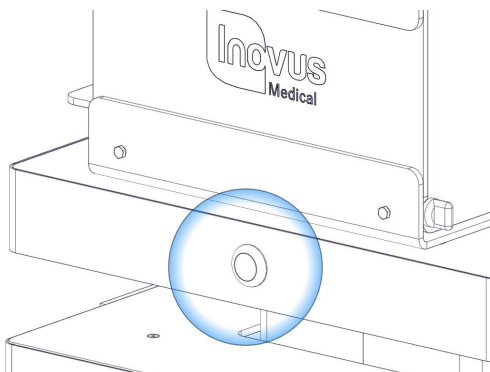
29 | If a WIFI connection isn't present, plug in the network cable provided with the system.



30 | Place your constructed simulator that you should have already assembled onto the top surface.



31 | Plug in the USB cable to the USB ports on the trolley system (Note: depending on the system you have purchased, USB port location may vary).



32 | Turn the system on using the power switch on the front. Once the computer has loaded up, select the LapAR™ icon on the desktop and follow the instructions inside the software.



e: info@inovus.org
t: +44 (0)1744 752 952
w: www.inovus.org



[@inovusmedical](https://www.instagram.com/inovusmedical)

All products contained in this catalogue are Copyright Inovus Ltd 2023
Full price list available on request: info@inovus.org
Full warranty details can be found on www.inovus.org